



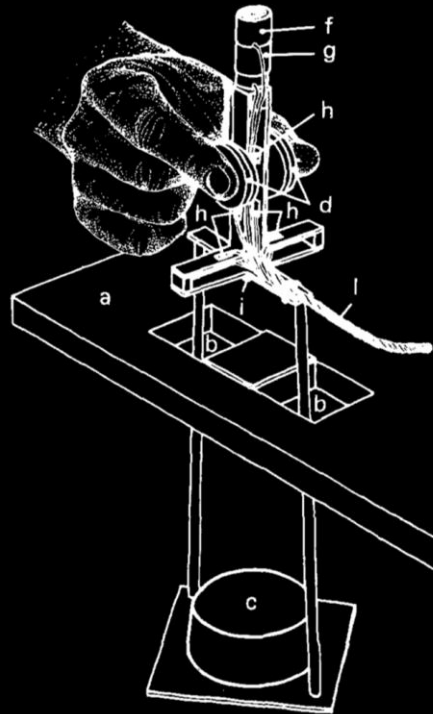
How frictional properties of a surface influence skin deformation on initial contact

Laurence Willemet and **Michaël Wiertlewski**

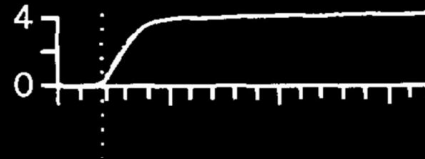
CNRS / Aix-Marseille Université, France
TU Delft, The Netherlands



Introduction - Friction influences grip

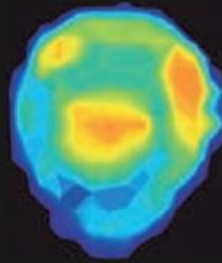


Load force, N

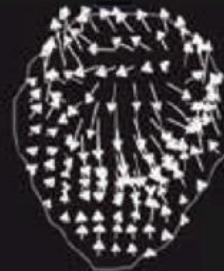
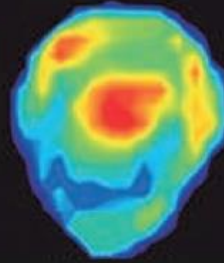


Introduction - Traction field

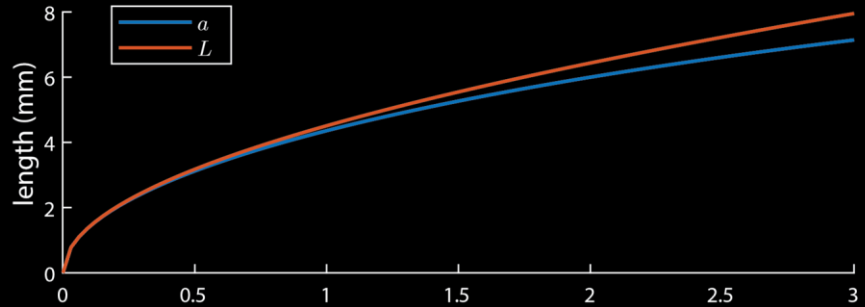
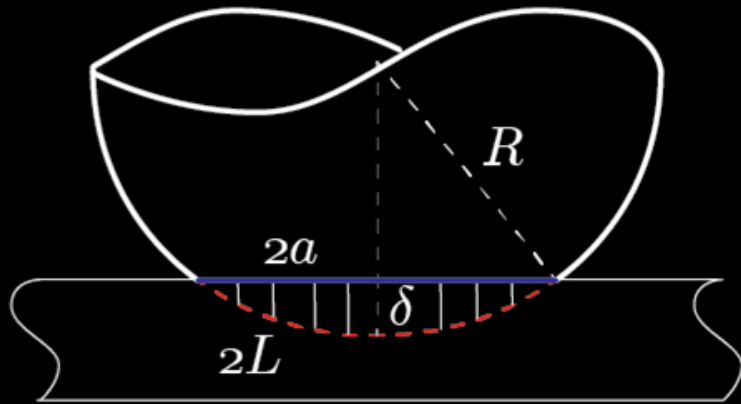
low friction



high friction



Hypothesis



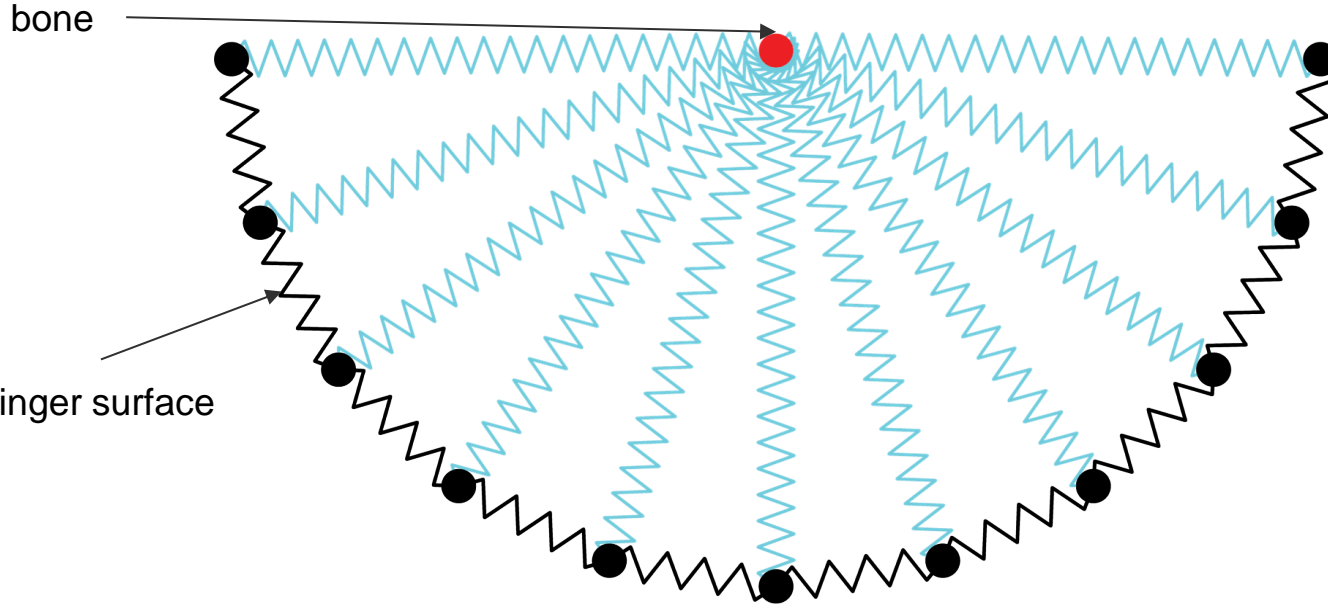
$$L = R \arccos\left(\frac{R - \delta}{R}\right)$$

$$a^2 = (R^2 - (R - \delta)^2)$$

Research problem

How does the **lateral traction field** develops from a **normal compression** on a high- or low-friction surface ?

Model of the finger surface - FDTD

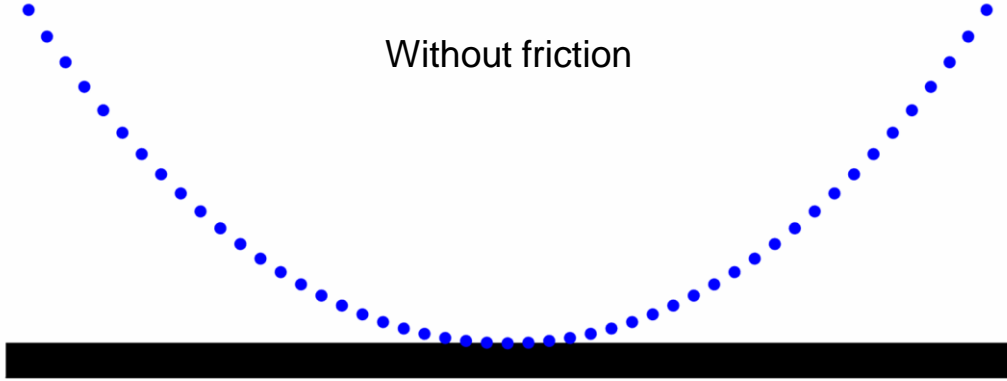


- Normal force:
Contact by
penalty method
- Tangential
force:
Friction using
Dahl model

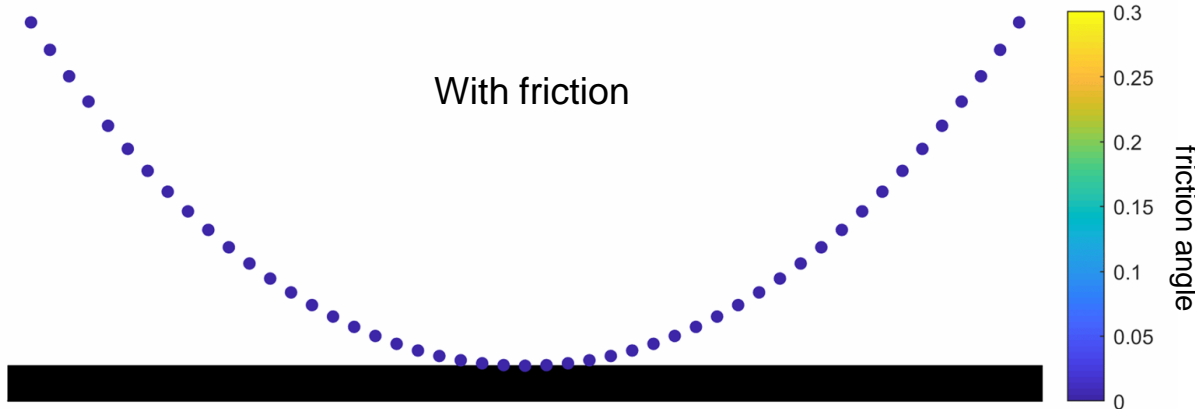
$$B \begin{bmatrix} \dot{U}_n \\ \dot{U}_t \end{bmatrix} + K \begin{bmatrix} U_n \\ U_t \end{bmatrix} + \begin{bmatrix} F_n \\ F_t \end{bmatrix}_{ext} = 0$$

Model predictions - Stress profile

Without friction

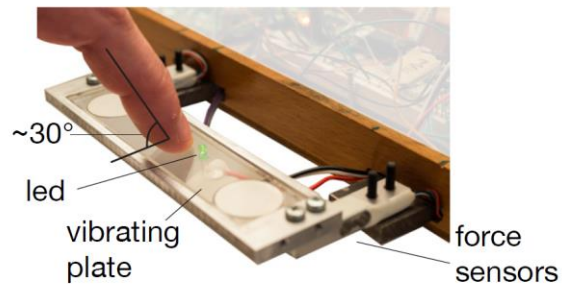


With friction

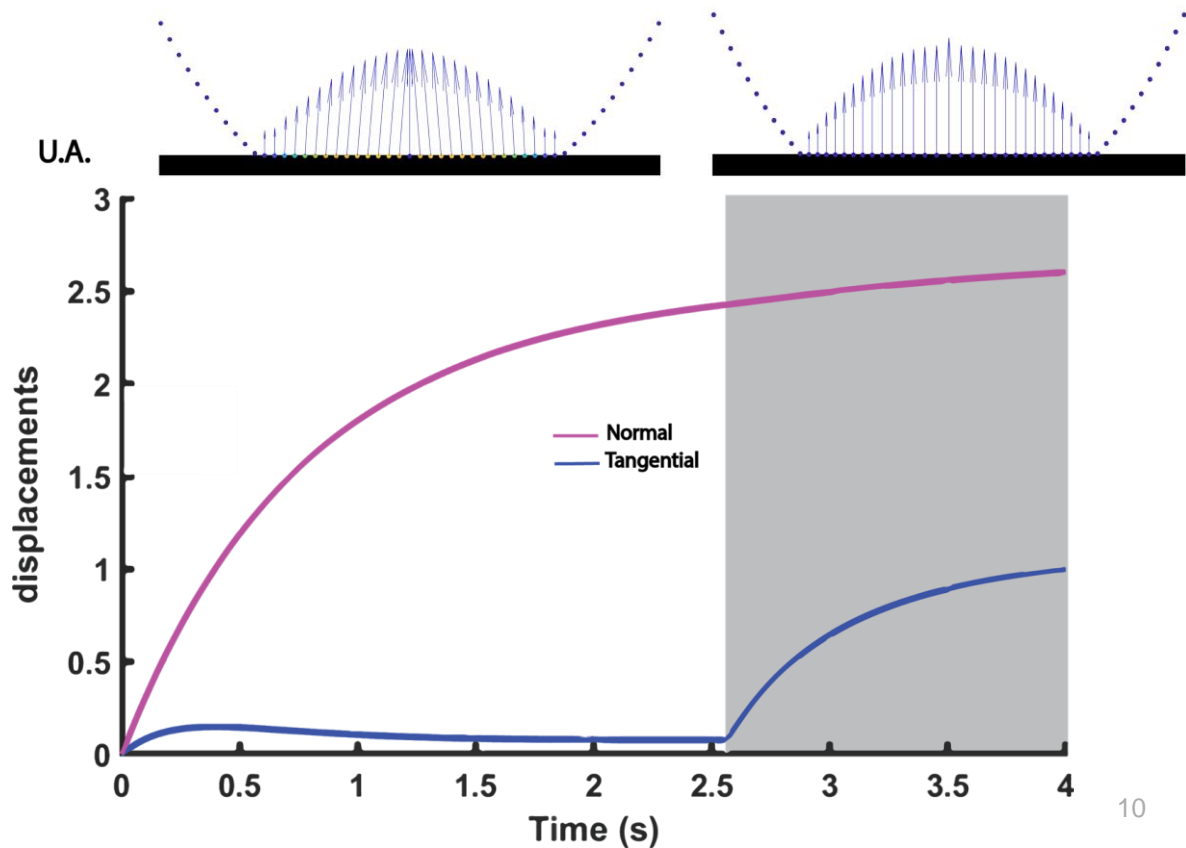


- Consistent with Hertzian contact
- Friction has an effect on elements spacing

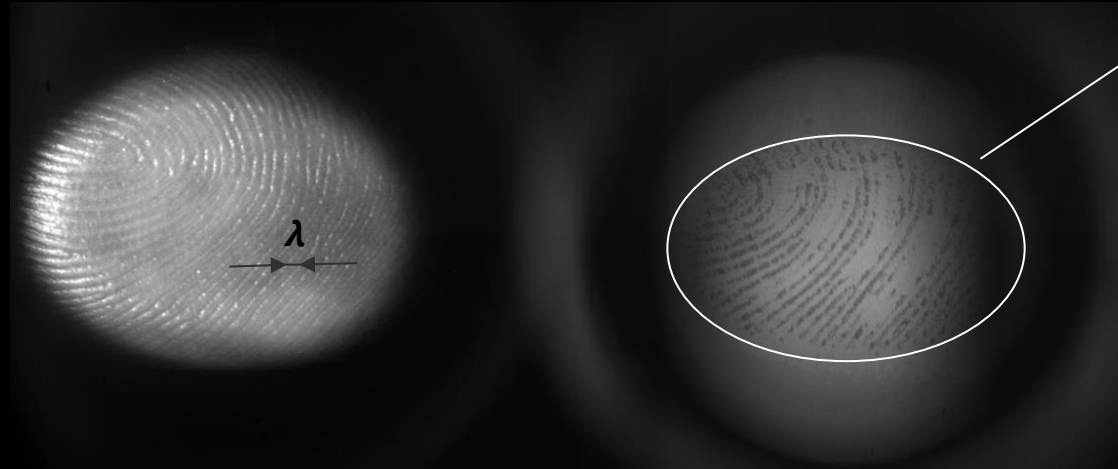
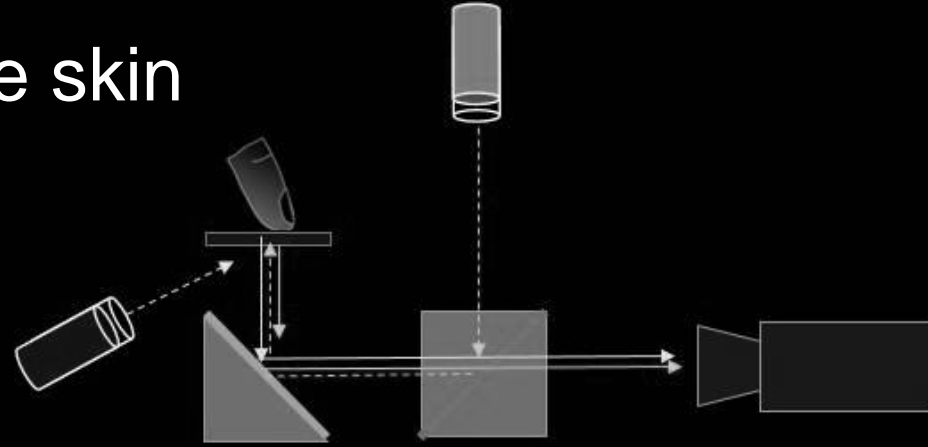
Model predictions - Ultrasonic click



Monnoyer et al. 2016

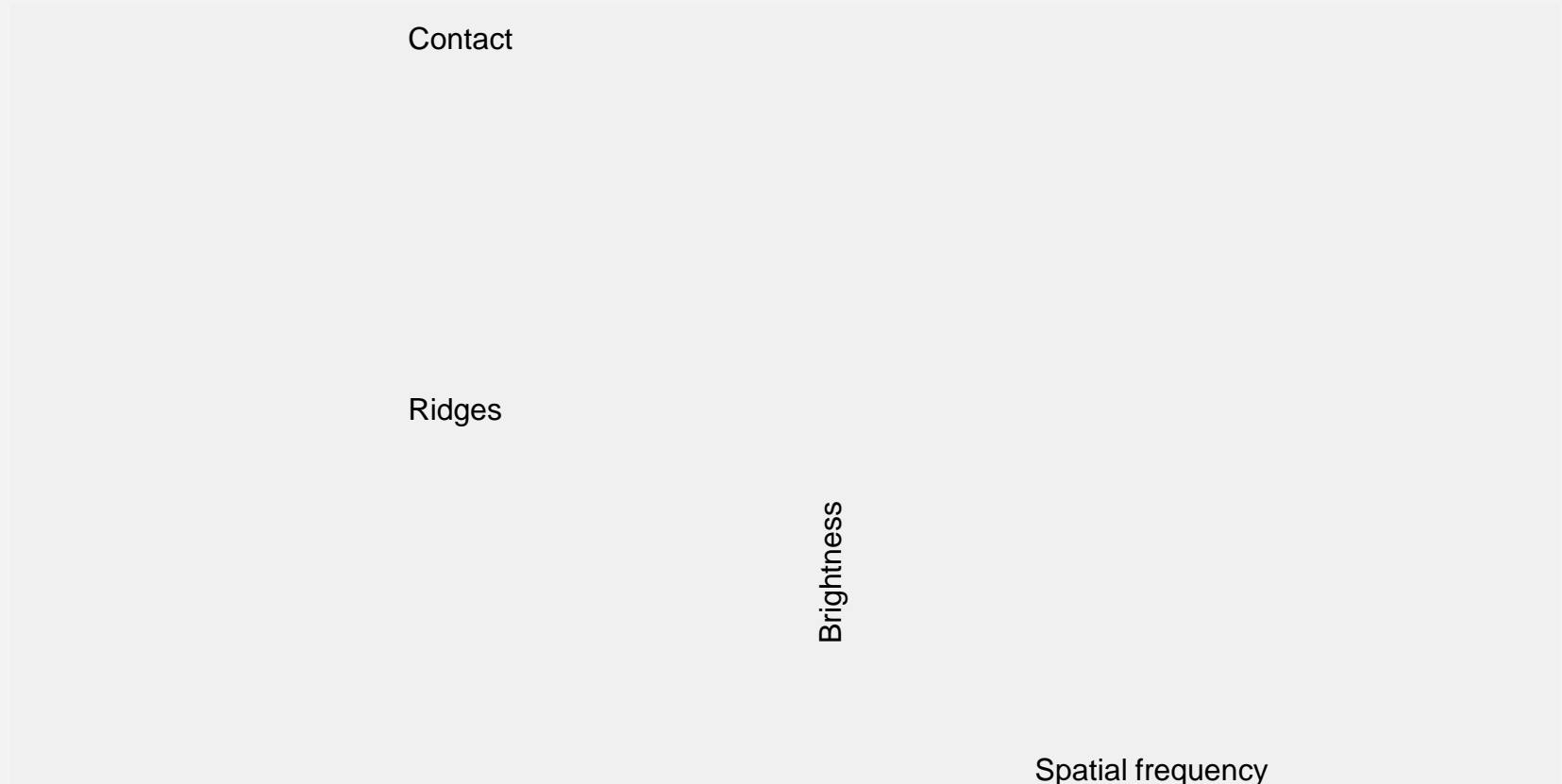


Imaging of the skin

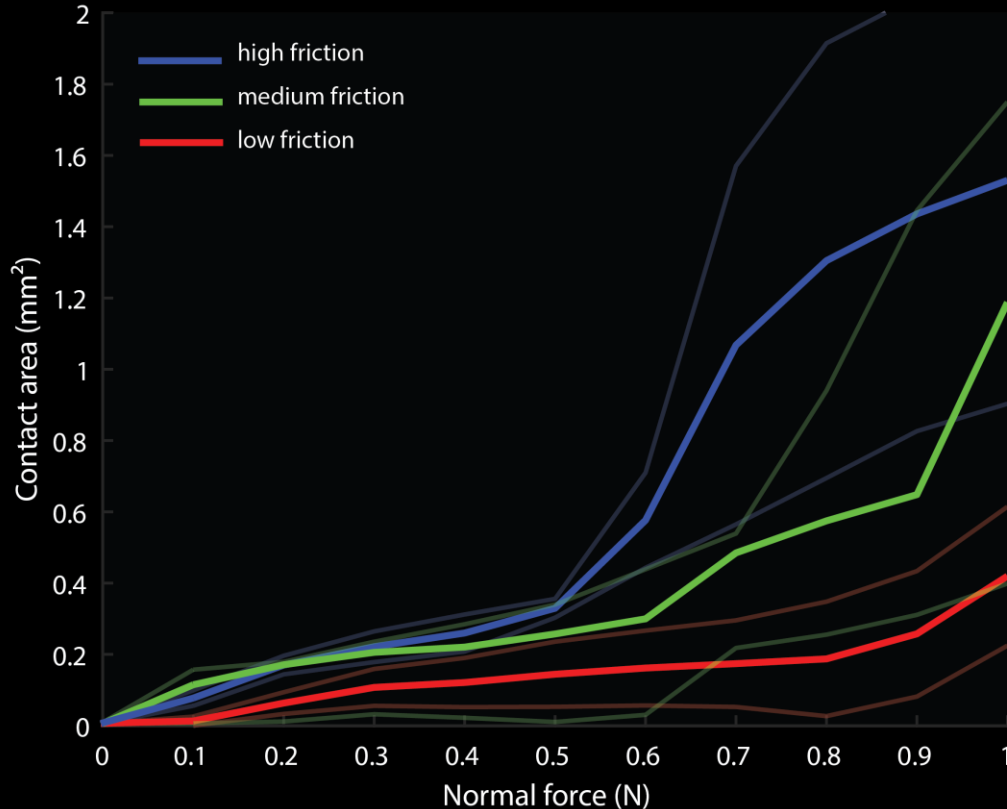


$$Ac = \frac{\sum pixel(I)}{resolution}$$

Imaging of the skin - with friction



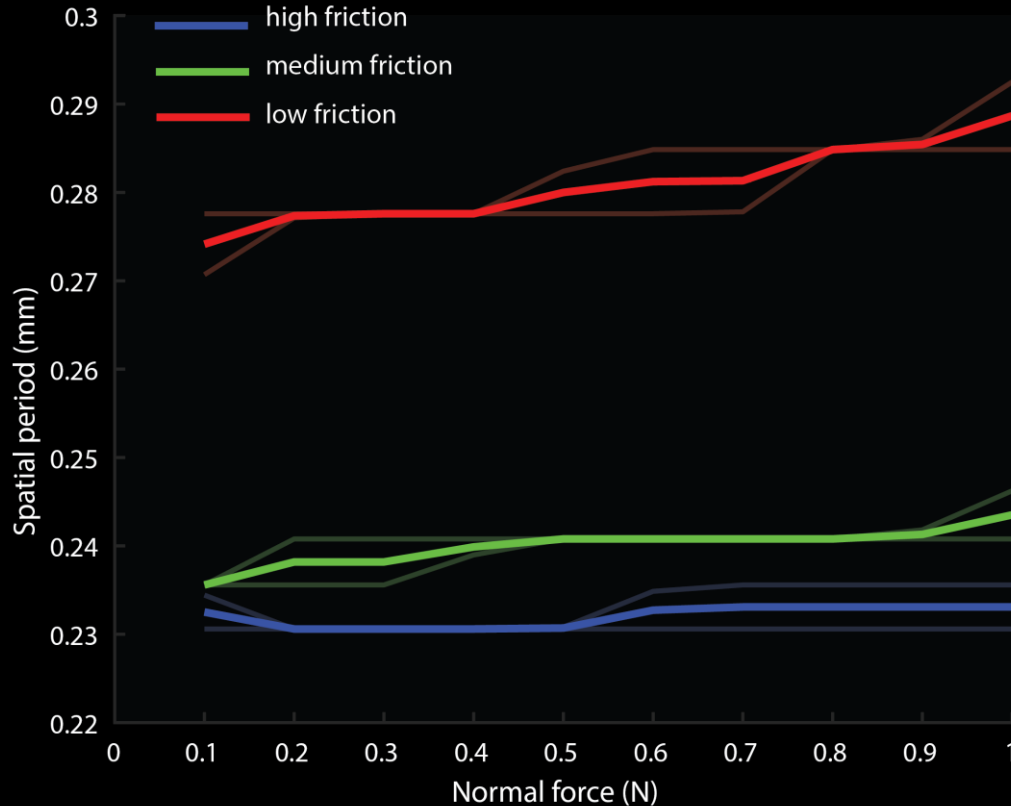
Imaging of the skin - Results



The area of contact increases with the normal force in the 3 conditions.

The higher the friction, the higher contact area for a given normal force.

Imaging of the skin - Results

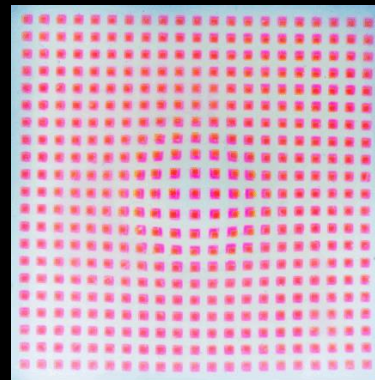


The higher the friction, the more the skin is compressed

Lateral strain reaches 20%.

Conclusion & Discussion

- Force is not a necessary cue for sensing friction
- The brain likely uses cues from the radial stretch distribution (see Prof. Birznieks' talk)
- Applications in surface haptics and in robotics
- Currently exploring the link with psychophysics



With friction

Lin et al., 2018

Acknowledgements



Thank you for your attention !

WIP 1 P.29